

REMOTE MONITORING SYSTEM

www.innoval.biz



35+
years of
experience

Innoval was born from **35 years of experience** of its technical and operational team in electronic Systems for industrial mobile vehicles.

100
customers

Innoval proudly serves a network of more than 100 clients across **multiple industries**, including **port terminals, construction sites, still mills** and **quarries**.

5000
systems

We design all our products by ourselves, **hardware** and **software**, for this reason our strong points are the customization and flexibility.

11
countries

Our electronic systems are installed on industrial machines operating **worldwide**.

OEM

We supply our systems to manufacturers of industrial mobile vehicles to have global control in real time, with Windows CE operating system, CAN-bus, CANopen, J1939, FMS protocols.



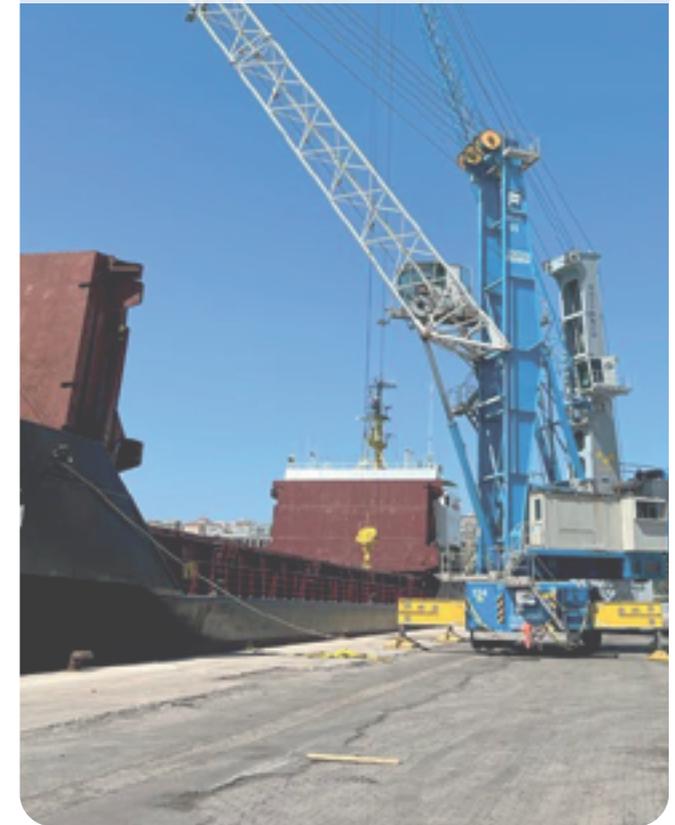
iOM[®]

We offer our electronic systems to end customers to be able to remotely monitor all the industrial mobile vehicles in their fleet with ONE system.
(Linux operating system)



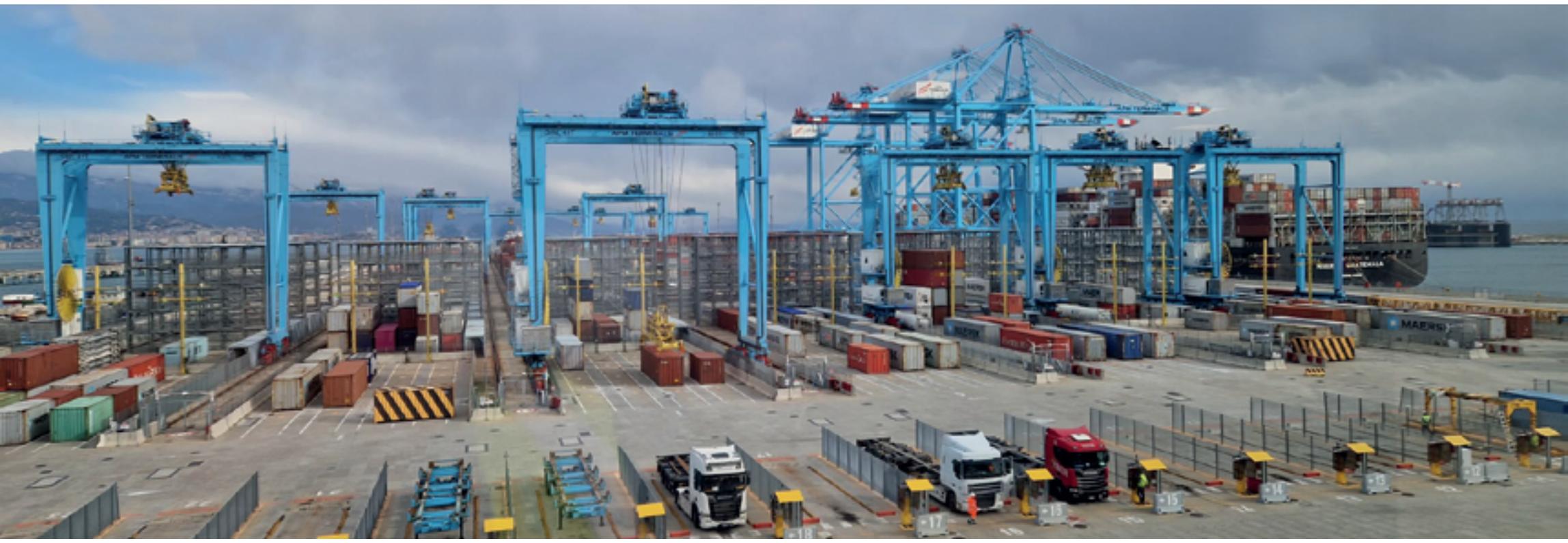
REVAMPING

To ensure that the vehicles are efficient even after several years, we carry out a complete electronic revamping of Mobile Harbor Cranes, Reachstackers, Forklift and Spreaders of different brands.





“**Internet of Machines** is a next generation machine telemetry and fleet remote monitoring System that can satisfy customer needs and used on machines of different types and brands.”



Industries



What do customers want?

Know if the machine is working

Know if the machine is operating correctly

Know the position of the machine

Inspect malfunctions easily and rapidly

Plan machine maintenance in advance

Quickly monitor all vehicles

What do INNOVAL provide?

Faster response to machine problems

Historical data for machine efficiency analysis

Machine fault predictions

Control unit with GPS/LTE on the machine

Real time alerts and warnings

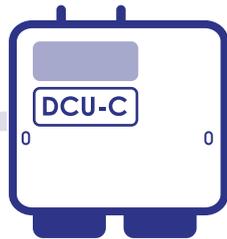
24/7 monitoring

A single interface to remote monitor all vehicle



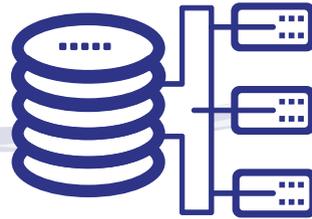
Innoval System includes:

CONTROL UNIT



Deployment of **DCU-C V2 control unit** in the machine and a VGA display (optional).
Linux operating system.

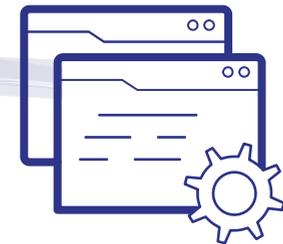
DATA COLLECTOR



DC runs **On Premise** or on **AWS Cloud**

Records machine data in a database allowing big data elaborations such as KPI (Key Performance Indicator) computation and long term analysis

DASHBOARD



Interactive **dashboard** for end user to view the interest data

What WE MANAGE



User authentication by NFC badge

Management of operator list enabled to the utilization

Checklist for the vehicle start

Operator detection (sensor located on the driver seat)



Recording of all faults, alarm, system by-pass

Spreader Status (TL seated, TL locked, TL unlocked)

Stability Reserve Status

Any active alarms

Signalization for motor speed at minimum for long time

Collision avoidance systems management

A.I. camera and UWB sensors management



Customizable maintenance checklist

Monitoring of traction unit

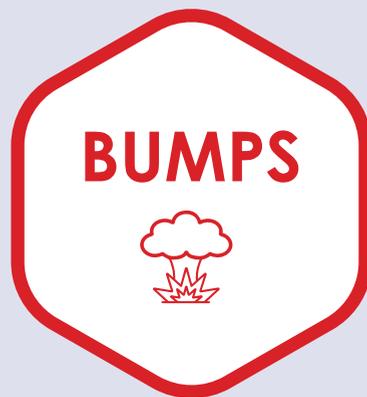
Monitoring of hydraulic parts

Suspension Monitoring

Steering monitoring

Tires pressure and temperature monitoring TPMS

Pre alarms and alarms based on abnormal conditions



Longitude and Latitude

Resultant and local acceleration (3-axis)

Direction of impact

Acceleration diagram

Speed data before and after impact

Map showing the accident path

Recording and sending images in case of bumps



Real time position of the machine via GPS tracking

Acceleration/Speed reduction based on areas

Trace route of vehicles

Geofencing



Date and Time of container handling start and ending

Travelled Distance of the machine during the handling

Container pick up and release height

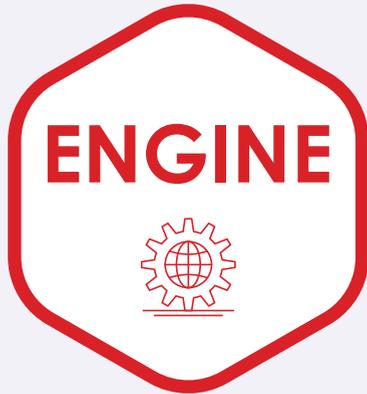
Container Handling time duration

Handled Container Size and Weight

Burnt fuel during the handling

Lifting Height of Spreader

Actual Load Lifted



Engine Oil Pressure and Temperature

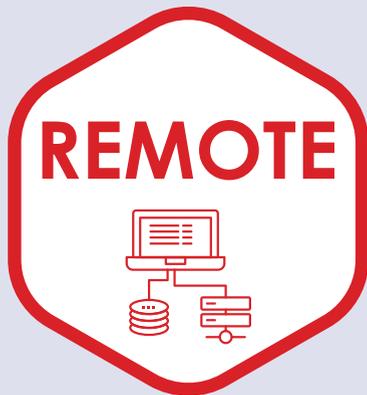
Engine Coolant Temperature

Hydraulic Lift Cylinders Pressure

Engine Fuel Level

Engine Torque

Engine Rpm



Inhibition to start the machine from remote

Real Time graphic monitoring of parameters and recording

Data encryption and compression before being sent to Server

Remote file updating

Remote software updating

Multi language software

VNC Virtual Network Computing

Dashboard

Customer may develop its own dashboard by accessing the saved machine data or INNOVAL can supply its own dashboard



WEB PORTAL BASED
(rest API based)



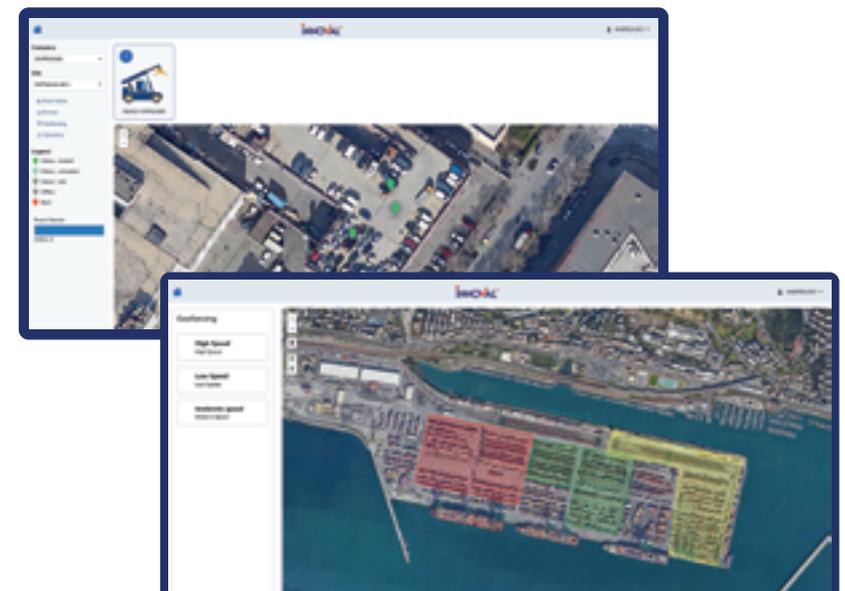
CONFIGURABLE
machine report measures



CUSTOMIZABLE
layout



MULTI
user/customer/dealer



DCU-C V2

Master Control Unit

The DCU-C V2 is a fully programmable automotive grade controller designed to be used as high performance master controller and Man-Machine-Interface (combined with an external VGA) in industrial vehicles.



SPECIFICATION:

CPU master: NXP i.MX6DL (2 x Cortex-A9 @ 800Mhz), Internal memory: 144 kByte RAM (OCRAM), 32i + 32d kByte L1 Cache, 512 kByte L2 Cache

External memory:

- Ram : 1 GByte DDR3, (2 / 4 GByte DDR3 optional)
- NAND Flash : 512 Mbyte, (1 / 2 / 4 GByte optional)
- 2 x Slot micro Sd-card (optional memory up to 2 x 32 Gbyte)

CPU slave (supervisor): NXP LPX5526 150 MHz (Cortex-M33), Memory: 256 kByte Flash, 144 kByte RAM

3 axis accelerometer and 3 axis gyroscope

3 axis magnetic-sensor (optional)

miniPCle slot for LTE/4G with micro SIM-Holder

M.2 slot (optional)

GPS module

OUTPUTS:

Standard VGA output

HDMI Output (optional)

Audio output (optional)

6 high-side PWM (4A max.), with self diagnostics and short circuit protection

5Vdc output/1A max. for external sensors

PoE 24Vcc/48Vcc output (optional)

INPUTS:

Audio input line or Mic (optional)

4 programmable analog inputs (0..5V, 0..25mA, 0..500mV or 0..25mA), one with programmable current pump (0..30mA).

16 digital inputs configurable via software for high-side or low-side operation, 4 usable as RPM / frequency inputs (up to 2kHz) and one as D+ input (controlled power down).

3 video (PAL/NTSC/SECAM) camera inputs (only one camera at a time handled)

CONNECTIVITY:

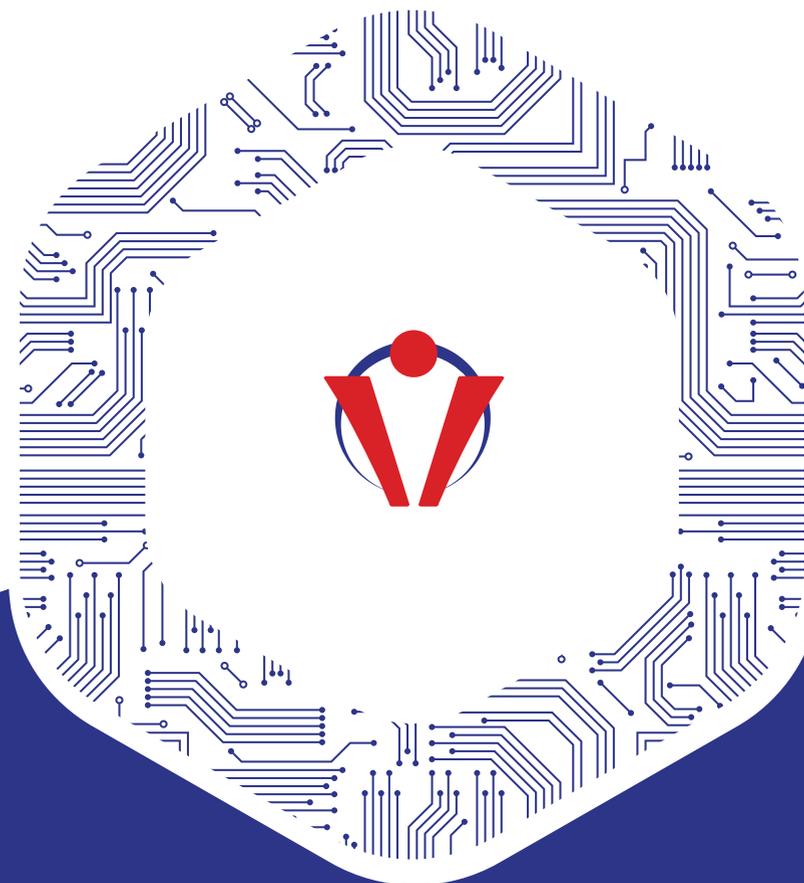
Serial interface RS232 or RS422/RS485 (configurable in SW) with programmable baud-rate from 1.2kBit/s to 115,2 kBit/s

2 USB 2.0 interfaces (Hi-speed): 1 Host and 1 Device

Ethernet 10/100 MBit/s

1 CAN-FD Bus (backward compatible with CAN 2.0B) from 125kBit/s to 8MBit/s

2 CAN-bus full 2.0B, programmable baud-rate from 125kBit/s to 1MBit/s, CANOpen and J1939 protocols (optional ISOBUS)



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